PIRM - Automated Battery Characterization

Team: sddec20-25 Advisor: Nathan Neihart Client: Solar Car Website: <u>http://sddec20-25.sd.ece.iastate.edu/</u> Team Lead: Joe DeFrancisco Email: <u>joedef@iastate.edu</u>

> Joe DeFrancisco, Ben Kenkel, Bryan Kalkhoff, Connor Luedtke, Ryan Willman, Kyle Czubak

Project Overview

- Best performance with matched batteries
- PrISUm Solar Car currently does not have an efficient way of characterizing batteries on a battery pack scale.
 - Currently the procedure is to measure the open circuit voltage of each battery and group them based on that measurement.
- Process is time consuming on large scale (1000 or more batteries)
- We will design and build an automated lithium battery characterizer



Current Status

Hardware:

- Completed design of following circuits:
 - Charging (mostly)
 - Load
 - Measurement
 - Microcontroller
- Model Overall Thermal Dissipation Requirements

Software:

- Flask app setup and running
 - Including database
 - HTML and CSS for frontend
- Microcontroller communication libraries being written



Semester Goals

- Have Revision 1 Hardware
- Completed Embedded Code
- Enclosure Designed
- Test Hardware
- Test Hardware and Software interaction
- Communicate between modules and app



Technical Challenges

- Measurement Accuracy
 - To have valid results, the voltage and current measurements will need to be accurate.
 - Main driver of the requirement is the internal resistance measurement, requiring μV level measurement accuracy.
- Unsupervised Operation
- Thermal Management
 - Full charge and discharge cycles will dissipate a lot of heat. This will need to be modeled so that proper heat sinking and cooling measures can be taken during design process.
- Bus Load
 - Uses multiple buses, I²C and CAN, and needs to balance the load of both buses



Next Steps

- Hardware
 - Schematic finalization
 - BOM Organization and streamlining
 - Start PCB layout
- Software
 - Embedded Library Creation
 - Communicate between modules and app
- Enclosure Design



Timeline



Tasks